Listing of the Claims

1. (Currently Amended) A magnetic resonance imaging method comprising: dividing k-space (100)—into a central region (102)—disposed at k-space center and one or more annular surrounding regions (104, 106)—having increasing distances from k-space center, the one or more annular surrounding regions including an outermost surrounding region (106)—having a largest distance from k-space center;

acquiring k-space samples in the central region (102);

subsequent to the acquiring of k-space samples in the central region, acquiring k-space samples in the one or more annular surrounding regions—(104, 106), the k-space samples in the outermost surrounding region (106)—being acquired last, the acquiring of k-space samples in at least the outermost surrounding region using a row-by-row data acquisition ordering in which each row of k-space samples acquired in the outermost surrounding region, together with selected already-acquired k-space data from the regions other than the outermost surrounding region, forms a completed data set for reconstructing an image plane; and

reconstructing each completed data set into a reconstructed image plane without waiting for all k-space samples in the outermost surrounding region to be acquired such that the reconstructing occurs at least partially concurrently with the acquiring.

- 2. (Original) The method as set forth in claim 1, further comprising: displaying each reconstructed image plane once it is available without waiting for the reconstructing of other image planes.
- 3. (Currently Amended) The method as set forth in claim 1, further comprising:

synchronizing the acquiring of k-space samples in the central region (102)-with a trigger signal, the trigger signal being one of: (i) a selected duration after administering a magnetic contrast agent bolus, (ii) detecting a change in a magnetic resonance signal intensity due to wash-in of a magnetic contrast agent bolus, (iii) detecting a gating signal, and (iv) detecting a selected physiological event.

4. (Currently Amended) The method as set forth in claim 1, further comprising:

selecting a plurality of magnetic resonance imaging parameters for the acquiring of k-space samples in the central region (102) and in the one or more annular surrounding regions (104, 106), the plurality of magnetic resonance imaging parameters including at least a data acquisition rate; and

determining the central (102) region using (i) the selected plurality of magnetic resonance imaging parameters and (ii) a time interval (120) for the acquiring of k-space samples in the central region (102).

- 5. (Currently Amended) The method as set forth in claim 1, wherein the central region (102) has a round or oval perimeter, and the outermost surrounding region (106) has a round or oval inner perimeter and a square or rectangular outer perimeter.
- 6. (Currently Amended) The method as set forth in claim 1, wherein the acquiring of k-space samples in the central region (102)-uses an acquisition ordering other than a row-by-row acquisition ordering.
- 7. (Currently Amended) The method as set forth in claim 6, wherein the acquiring of k-space samples in the central region (102)-uses a random or pseudorandom ordering.
- 8. (Currently Amended) The method as set forth in claim 7, further comprising:

synchronizing the acquiring of k-space samples in the central region (102)-with the administering of a magnetic contrast agent bolus.

9. (Original) The method as set forth in claim 6, further comprising: sorting the k-space samples of the central region into a row-by-row ordering.

- 10. (Currently Amended) The method as set forth in claim 1, wherein the one or more annular surrounding regions (104, 106) include at least two surrounding regions, and the acquiring of k-space samples in the one or more annular surrounding regions other than the outermost surrounding region uses a random or pseudorandom ordering.
- 11. (Currently Amended) The method as set forth in claim 1, wherein the one or more annular surrounding regions (104, 106) include at least two surrounding regions, and the acquiring of k-space samples in every annular surrounding region including the outermost surrounding region uses a row-by-row acquisition ordering.
- 12. (Currently Amended) The method as set forth in claim 1, wherein each k-space sample (100) is a readout line of k-space.
- 13. (Original) The method as set forth in claim 1, wherein the acquiring of k-space samples in at least the outermost surrounding region using a row-by-row acquisition ordering includes:

acquiring the k-space samples using a serpentine row-by-row acquisition ordering.

14. (Original) The method as set forth in claim 1, wherein the acquiring of k-space samples in at least the outermost surrounding region using a row-by-row acquisition ordering includes:

applying secondary coordinate magnetic field gradients to traverse each row of k-space samples; and

switching to each new row of k-space samples by applying a primary coordinate magnetic field gradient, the primary coordinate being generally transverse to the secondary coordinate.

- 15. (Original) The method as set forth in claim 1, wherein the acquiring of k-space samples in at least the outermost surrounding region using a row-by-row acquisition ordering includes:
- (i) acquiring a first row of k-space samples by traversing secondary coordinate positions in a positive direction at a first primary coordinate position;
- (ii) applying a primary coordinate magnetic field gradient to move to a second primary coordinate position;
- (iii) acquiring the second row of k-space samples by traversing secondary coordinate positions in a negative direction at the second primary coordinate position; and
- (iv) repeating (i), (ii), and (iii) to acquire a plurality of rows of k-space samples indexed by the primary coordinate.
- 16. (Currently Amended) The method as set forth in claim 15, wherein the primary coordinate is a slice coordinate, the secondary coordinate is a phase-encode coordinate orthogonal to the slice coordinate, and each k-space sample (100)—is a readout line along a third coordinate orthogonal to both the slice and phase-encode coordinates.
- 17. (Original) The method as set forth in claim 1, wherein the acquiring of k-space samples in at least the outermost surrounding region using a row-by-row acquisition ordering includes:
- (i) acquiring a first contiguous portion k-space samples along a row within the outermost annular surrounding region;
 - (ii) skipping at least samples along the row contained in the central region;
- (iii) acquiring a second contiguous portion k-space samples along the row within the outermost annular surrounding region, the second contiguous portion k-space samples along the row being separated from the first contiguous portion k-space samples along the row by at least the central region; and

repeating (i), (ii), and (iii) for each row of the row-by-row acquisition.

18. (Currently Amended) A magnetic resonance imaging apparatus comprising: a magnetic resonance imaging scanner (10)-imaging an associated imaging subject (16);

a magnetic resonance imaging controller (50) performing a method including:

- (i) dividing k-space (100)-into a central region (102)-disposed at k-space center and one or more annular surrounding regions (104, 106) having increasing distances from k-space center and including an outermost surrounding region (106)-of largest distance from k-space center,
- (ii) determining an optimum time for imaging a magnetic contrast agent bolus,
- (iii) acquiring k-space samples in the central region (102) at about the optimum time, and
- (iv) after acquiring the k-space samples in the central region, acquiring k-space samples in the one or more annular surrounding regions (104, 106), the acquiring in at least the outermost surrounding region (106) using a plane-by-plane data acquisition ordering in which all k-space samples in the outermost surrounding region belonging to a current k-space plane are acquired to complete the current k-space plane before samples in the outermost surrounding region belonging to other k-space planes are acquired; and
- a reconstruction processor (62)—that reconstructs the completed current k-space plane into a reconstructed plane image without waiting for other k-space planes to be completed.
- 19. (Currently Amended) The magnetic resonance imaging apparatus as set forth in claim 18, wherein the acquiring of k-space samples in the central region (102) includes:

acquiring k-space samples in the central region (102) using an ordering other than a plane-by-plane ordering.

20. (Currently Amended) The magnetic resonance imaging apparatus as set forth in claim 18, wherein the acquiring of k-space samples in the central region (102) includes:

acquiring k-space samples in the central region (102)—using a random or pseudorandom ordering.

- 21. (Currently Amended) The magnetic resonance imaging apparatus as set forth in claim 20, further comprising:
- a display device (68)—that displays each reconstructed plane image once the reconstruction processor (62)—completes reconstruction of the corresponding k-space plane, without waiting for the reconstruction processor to reconstruct other k-space planes.
- 22. (Currently Amended) A magnetic resonance imaging apparatus comprising: means for dividing k-space (100)-into a central region (102)-disposed at k-space center and one or more annular surrounding regions (104, 106)-having increasing distances from k-space center, the one or more annular surrounding regions including an outermost surrounding region (106)-having a largest distance from k-space center;

means for acquiring k-space samples in the k-space - (100), the k-space samples in the central region (102)—being acquired first, the k-space samples in the outermost surrounding region (106)—being acquired last, the k-space samples in at least the outermost surrounding region being acquired using a row-by-row data acquisition ordering in which each row of k-space samples acquired in the outermost surrounding region completes a k-space plane; and

means (62) for reconstructing each completed k-space plane into a reconstructed image plane without waiting for all k-space samples in the outermost surrounding region (106)-to be acquired.

- 23. (Original) The apparatus as set forth in claim 22, wherein the acquiring means includes:
- (i) means for acquiring a row of k-space samples by traversing secondary coordinate (c_s) positions in a positive direction at a first primary coordinate position (c_p);
- (ii) means for applying a primary coordinate (c_p) magnetic field gradient to move to a second primary coordinate (c_p) position;
- (iii) means for acquiring the second row of k-space samples by traversing secondary coordinate (c_s) positions in a negative direction at the second primary coordinate (c_p) position; and
- (iv) means for repeatedly invoking the means (i), (ii), and (iii) to acquire a plurality of rows of k-space samples indexed by the primary coordinate (c_p).
- 24. (Currently Amended) The apparatus as set forth in claim 22, wherein the acquiring means acquires at least the central region (102) using other than a row-by-row acquisition ordering, and the reconstructing means (62) includes:

means (150)—for sorting k-space samples acquired in other than a row-by-row acquisition ordering into a row-by-row ordering.

25. (Currently Amended) The apparatus as set forth in claim 22, wherein the reconstructing means (62) includes:

means (150)-for organizing k-space samples of the completed k-space plane from the central region (102) and from the one or more annular surrounding regions (104, 106) into a k-space plane data set organized row-by-row;

means (152)—for Fourier transforming each k-space sample of the completed k-space plane in a first direction to recover spatial content in the first direction; and

means (162)-for Fourier transforming the k-space plane data set organized row-by-row in a second direction transverse to the first direction to recover spatial content in the second direction.